Stephen Gerald McGill, Jr.

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Summary

Experienced researcher in machine learning, computer vision and kinodynamic planning techniques for driver intent estimation and risk mitigation for autonomous car product. Proven team leader through DARPA Robotics Challenges and international RoboCup competitions with strong foundations in field robotics, human interfaces, funding allocation, and personnel management. Invited to public speaking engagements and international research talks, managed institutional relationships and regarded as valuable teaching assistant, which demonstrate strong communication and social skills.

Experience

Research Scientist, Toyota Research Institute, Cambridge, MA	June 2016 – Present
Driver intent estimation for Guardian parallel autonomy vehicle	
Software Team Leader, Team THOR, DARPA Robotics Challenge	October 2012 – May 2016
Finals: 13th of 24, Challenge Trials: 9th of 16	
Team Leader, Team DARwIn and Team THORwIn, RoboCup	January 2010 – July 2016
Louis Vuitton Cup Winner 2015; First place 2011-2015	
Research Fellowship, Sapienza University of Rome	December 2013 – July 2014
Transatlantic Partnership for Excellence in Engineering Award	
Technology Disclosure Fellow, UPenn Center for Technology Transfer	May 2012 – September 2013
Residential Advisor and Coordinator, UPenn Residential Services	August 2011 – December 2013
Machine Learning Software Intern, Capital IQ, New York, NY	May 2010 – August 2010
Technology Policy Research Intern, IEEE-USA, Washington, DC	June 2009 – August 2009
Hardware and Grant Writing Intern, Dragonfly Pictures, Essington, PA	December 2008 – January 2009
Network Equipment Intern, Communications Test Design, West Chester, PA	June 2006 – August 2007

Education

Doctor of Philosophy, Electrical Engineering. May, 2016

University of Pennsylvania, Philadelphia, PA

Dissertation: Scaled Autonomy for Networked Humanoids. Advisor: Daniel D. Lee

2010 Ashton Fellowship, 2011 NSF GRFP Honorable Mention

Master of Science in Engineering, Robotics. May, 2011

University of Pennsylvania, Philadelphia, PA

Bachelor of Science in Engineering, Majors: Electrical Engineering, Computer Science. May, 2010

University of Pennsylvania, Philadelphia, PA

Honors: Graduated Cum Laude, Dean's List 2009-10

2009 Engineering Alumni Society E. Stuart Eichert, Jr. Award

Invited Talks

Humans-in-the-Loop for Autonomous Driving Development, Museum of Science, Boston	May & October, 2017
Human-in-the-Loop Perception, Planning and Control, MIT 2.12	November, 2017
Motion and Perception for Humanoids in Field Robotics, Columbia University CS 6731	April, 2016
Scaled Autonomy for Networked Humanoids, Temple University	February, 2016
Robotics for the Insurance Industry and the Workforce, Wharton Executive Education: KPMG	December, 2015
Global Insurance Academy	
Scaled Autonomy for Networked Humanoids, Bucknell University	October, 2015
Human Interface Control of Next Generation Humanoids, TU Darmstadt, Germany	March, 2014
Beyond DARwIn: Applying Concepts from Robot Soccer, TU Darmstadt, Germany	June, 2012
Robots for Life: On the Path to Robotic Healthcare, TEDxColumbiaEngineering, New York	October, 2012
Robotics and Energy, Young Researchers Transatlantic Academy, Aachen, Germany	June, 2012
Team DARwIn, TEDxPhoenixville, Pennsylvania	September, 2011

Selected Publications

Stephen G McGill Systems and methods for dynamically adjusting a vehicle trajectory according to deviations of a driver from expected inputs. Patent Pending.

Stephen G McGill, Seung-Joon Yi, Hak Yi, Minsung Ahn, Sanghyun Cho, Kevin Liu, Daniel Sun, Bhoram Lee,

Heejin Jeong, Jinwook Huh, Dennis Hong, and Daniel D. Lee.

Team THOR's Entry in the DARPA Robotics Challenge Finals.

Journal of Field Robotics, Volume 34, Issue 4, June 2017

Stephen G McGill, Seung-Joon Yi and Daniel D. Lee. *Low Dimensional Human Preference Tracking for Motion Optimization*.

IEEE-RAS International Conference on Robotics and Automation, 2016.

Stephen G McGill, Seung-Joon Yi, Daniel D. Lee.

Team THOR's Adaptive Autonomy for Disaster Response Humanoids.

15th IEEE-RAS International Conference on Humanoid Robots, 2015.

Seung- Joon Yi, **Stephen G McGill**, Larry Vadakedathu, Qin He, Inyong Ha, Jeakweon Han, Hyunjong Song, Michael Rouleau, Byoung-Tak Zhang, Dennis Hong, Mark Yim, Daniel D. Lee.

Team THOR's Entry in the DARPA Robotics Challenge Trials 2013.

Journal of Field Robotics, Volume 32, Issue 3, 2015.

Seung-Joon Yi, Stephen G McGill, Byoung-Tak Zhang, Dennis Hong, Daniel D. Lee.

Active stabilization of a humanoid robot for real-time imitation of a human operator.

12th IEEE-RAS International Conference on Humanoid Robots, 2012.

Stephen G McGill and Daniel D. Lee.

Cooperative humanoid stretcher manipulation and locomotion.

11th IEEE-RAS International Conference on Humanoid Robots, 2011.

Teaching

Coursera Teaching Assistant, State Estimation and Learning for Robotics	Fall 2015 – Spring 2016
Teaching Assistant, ESE650: Learning in Robotics	Spring 2012 – Spring 2015
Teaching Assistant, ESE450, ESE 451: Senior Design	Fall, Spring 2013 – 2015
Teaching Assistant, Introduction to Robotics Technology	Summer 2013
UPenn Summer Academy in Applied Science and Technology	
Teaching Assistant, ESE410/510: Design of Mechatronic Systems	Fall 2011
Teaching Assistant, CIS110: Introduction to Computer Programming (Java)	Spring 2009
Teaching Assistant, ESE116: C Programming in the Unix Environment	Fall 2008
Residential and Teaching Assistant, Teaching Computer Science Basics UPenn Summer Academy in Applied Science and Technology	Summer 2008

Service

FIRST Robotics Mentor, Team 1168: Malvern Robotics

High School Student Mentoring, GRASP Lab Robotics

Camp Counselor, Muscular Dystrophy Association

Computer Lab Installation in Ghana, Communitech, UPenn

November 2014 – Present
June 2015 – August 2015
June 2015, 2016
August 2008

Skills

C, Lua, MATLAB, JavaScript, Python, SQL, Java torch7, pytorch, Node.js, UNIX, git, THREE.js